

Discussion on:  
Dynamic sparse predictive regressions  
Mauro Bernardi, Daniele Bianchi, Nicolas Bianco

Anna Simoni (*CREST, CNRS, École Polytechnique, ENSAE*)

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Very interesting paper.

I've enjoyed reading it.

Aim:

- **Predicting** the dynamics of economic variables (*e.g.* forecasting inflation, asset returns);
- **large number** of predictors;
- the relevance of the predictors may change over time, hence **sparsity** potentially varying over time.

**Prediction** is based on a Gaussian time-varying parameter regression model:  
for  $t = 1, \dots, n$ ,

$$y_t = x_t' \tilde{\beta}_t + \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0, \sigma_t^2), \quad (1)$$

where  $x_t$  and  $\tilde{\beta}_t$  are  $p$ -dimensional,  $\tilde{\beta}_t$  is sparse, and  $p$  might be large compared with  $n$  (high-dimension).

**High-dimension** is dealt with by assuming **sparsity** and **time-varying sparsity** is induced through the following prior:

1) reparametrization:

$$\tilde{\beta}_t = \Gamma_t \beta_t$$

$$\Gamma_t = \text{diag}(\gamma_{j,t}), \quad \{\gamma_{j,t}\} \in \{0, 1\}^{pn}, \quad \text{where } j = 1, \dots, p, \quad t = 1, \dots, n;$$

2) prior: Bernoulli-Gaussian (**BG**) dynamics

2.1 Random walk for  $\beta_{j,t}$ : for every  $j = 1, \dots, p$

$$\beta_{j,t} = \beta_{j,t-1} + v_{j,t}, \quad v_{j,t} \sim \mathcal{N}(0, \eta_j^2)$$

and  $\beta_{j,0} \sim \mathcal{N}(0, \kappa_0 \eta_j^2)$  (in vector form  $\beta_j \sim \mathcal{N}_{n+1}(0, \eta^2, Q^{-1})$  with  $Q$  tridiagonal);

2.2 stochastic volatility:  $h_t = \log(\sigma_t^2)$  and

$$h := (h_0, \dots, h_n) \sim \mathcal{N}_{n+1}(0, \nu^2 Q^{-1}).$$

(Alternative: homoskedasticity (**BGH**)).

2.3 Persistent stochastic process for  $P(\gamma_{j,t} = 1)$ :

$$\gamma_{j,t} | \omega_{j,t} \stackrel{ind.}{\sim} \text{Be}(p_{j,t}), \quad \omega_{j,t} = \frac{p_{j,t}}{1 - p_{j,t}}$$

and  $\omega_j := (\omega_{j,0}, \dots, \omega_{j,T}) \sim \mathcal{N}_{n+1}(0, \xi_j^2 Q^{-1})$ . The components  $(\gamma_{j,1}, \dots, \gamma_{j,n})$  are correlated with respect to the marginal prior, given  $\xi_j^2, Q$ .

## 2.4 Priors on hyperparameters.

3) semi-parametric Variational Bayes algorithm based on two assumptions on the set of approximating densities:

- mean-field factorisation,
- parametric approximation for the density of  $h$  and the probability of  $\gamma_{j,t}$  (to have smooth sequence of posterior inclusion probabilities).

The main novelty of this prior w.r.t. existing literature is the prior of  $\gamma_{j,t}$  which allows persistency through correlation (in the marginal).

**Question.** Can  $\gamma_{j,0}$  be zero? not clear from the text.

**Remark.** Probabilistic structure of this prior. Is it useful to write the BG prior as a spike-and-slab prior?

$$\tilde{\beta}_{j,t} | \beta_{j,t-1}, \gamma_{j,t} \sim \gamma_{j,t} \mathcal{N}(\beta_{j,t-1}, \eta_j^2) + (1 - \gamma_{j,t}) \delta_0(\tilde{\beta}_{j,t})$$

under the assumption  $\tilde{\beta}_{j,t} \perp\!\!\!\perp \gamma_{j,t-1} | \beta_{j,t-1}, \gamma_{j,t}$ .

- The spike part does not depend on  $\beta_{j,t-1}$ ;
- The slab part is persistent and depends on  $\beta_{j,t}$  not on  $\tilde{\beta}_{j,t}$ , so the **past sparsity pattern** affects the value of  $\tilde{\beta}_{j,t}$  only through  $\gamma_{j,t}$ ;

- the conditional marginal is

$$\pi(\tilde{\beta}_{j,t} | \beta_{j,t-1}, p_{j,t}) \sim p_{j,t} \mathcal{N}(\beta_{j,t-1}, \eta_j^2) + (1 - p_{j,t}) \delta_0(\tilde{\beta}_{j,t})$$

and then we can integrate out  $p_{j,t-1}$ .

This prior competes with the following state-of-the-art priors:

- Koop & Korobilis (2022):
  - soft-spike-and-slab prior with two normals, one of them with variance  $\rightarrow 0$
  - the variance of  $\tilde{\beta}_{j,t}$  vary over time.
- Rockova & McAlinn (2021): soft-spike-and-slab prior

$$\tilde{\beta}_{j,t} | \tilde{\beta}_{j,t-1}, \gamma_{j,t} \sim \gamma_{j,t} \psi_1(\mu_{j,t}, \eta_j^2) + (1 - \gamma_{j,t}) \psi_0(\lambda_0),$$

where

- $\mu_t = \phi_0 + \phi_1(\tilde{\beta}_{t-1} - \phi_0)$  with  $|\phi_1| < 1 \Rightarrow$  motivation to take  $\phi_1 = 1$ ;
- $\psi_0$  could be Laplace density.
- The probability of  $\gamma_{j,t}$  depends on  $\tilde{\beta}_{j,t-1}$  explicitly.

**Question.** Comparison of the persistency of the sparsity through time induced by the two priors?

Other questions:

- $\gamma_{jt} \sim \text{Bern}(p_{jt})$ ,  $\frac{p_{jt}}{1-p_{jt}} = \omega_{jt}$  and  $\omega_j \sim \mathcal{N}_{n+1}(0, \xi_j^2 Q^{-1})$ . Motivation for this prior? Could you for instance consider  $p_{jt} = p_j$  with  $p_j \sim \text{Beta}$ ? This would also give correlated components.
- Small number of hyperparameters compared to competitor priors but persistency. What if persistency is not satisfied by the true  $\tilde{\beta}_t$ ?
- Simulations: try  $AR(1)$  with less persistency ( $\phi_1 = 0.98$  currently) for the active coefficients.
- How large  $n$  can be? interesting to see the effect of  $n$  in the simulations.
- Correlation between predictors?

We can re-interpret this model in terms of **groups**, where

- the components of each group show dependency structure
- sparsity among groups and within group  $\Rightarrow$  **bi-level sparsity**.
- In the paper: sparsity at one level.

Every covariates  $j$  defines a group:

$$\tilde{\beta}_j := (\tilde{\beta}_{j,0}, \dots, \tilde{\beta}_{j,n}) = \Gamma_j \beta_j$$

with  $\Gamma_j = \text{diag}(\gamma_{j,t})$ ,  $t = 0, \dots, n$  and  $\beta_j$  is  $(n + 1)$ -vector. Here  $\gamma_{j,t}$  are standard deviations, not binary variables.

- There are  $p$  (potentially active) groups;
- each group has  $n + 1$  (potentially active) components.

The group structure is useful:

- to reduce dimension;
- if one believes there are predictors that are never relevant.

Then, one can for instance extend Mogliani & Simoni (2023, wp) to allow for temporal dependence inside each group.

- Mogliani & Simoni (2023, wp) consider a **double spike-and-slab** prior.
- Comparison of the two priors would be interesting.

In practice: extend your GMRF prior for  $\beta_j$  to a hard-spike-and-slab (with a Dirac at 0). That is, there is a non-zero probability that a group is inactive.

**Question.** suppose some predictors are never relevant (as in your simulation), what is the computational cost?